



# Advanced Exploration Systems (AES) Core Flight Software (CFS) Project

- Summary of Products (FY13-FY15)
  - Plans for FY16
- Additional CFS Projects at JSC

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# CFS AES Project

## Product Summary FY13 & FY14



### ◆ FY13 Products

- CFS on Orion/B787 Platform – CFS on Partitioned Green Hills RTOS
- Quad-Voting CFS System – CFS on Partitioned VxWorks RTOS, synchronizing & voting 4 computers
- CFS within Trick Simulation
- Distributed CFS – network-based software bus additions
- Reusable Certification Test Suite (begin)

### ◆ FY14 Products

- Class A CFS Certification on Integrity ARINC-653/Orion Primary Flight Platform
- Performance Monitoring Tool
- CFS Synch & Voting Software Development
- Product Line
- Command & Data Dictionary Ground Database Tool
- Education/Outreach



# AES CFS FY15 Software Tasks & Status



## ◆ Major Tasks for FY15

- CFS Class A Certification on VxWorks/LEON3
  - Will be delivered to Orion program an GOTS after merge with main product line
  - Full-coverage UT Assert unit test suite
  - API unit tests
  - Vertical Integration tests
- Other AES Projects:
  - Integration of AES Habitat Apps with CFS Message Bus/SBN
  - Migration of Autonomy Applications within CFS Framework

Complete

Ongoing, Much progress

## ◆ Additional Tasks for FY15

- Orion Backup Prototype/Analysis with CFS/LEON3

Complete (*Demo Jan 2015*)
- Generic Command & Telemetry Apps
  - CFS Communication Interface with C3I Standard

V1 Complete (*Demo 9/2015*)
- CFS Synch & Voting Software Development

Complete (*Demo 9/2015*)
- Command & Data Dictionary Tools

Added TTGbE (*Demo 9/2015*)
- Product Line

2 Tools (*Demo 9/2015*)
- Education / Outreach

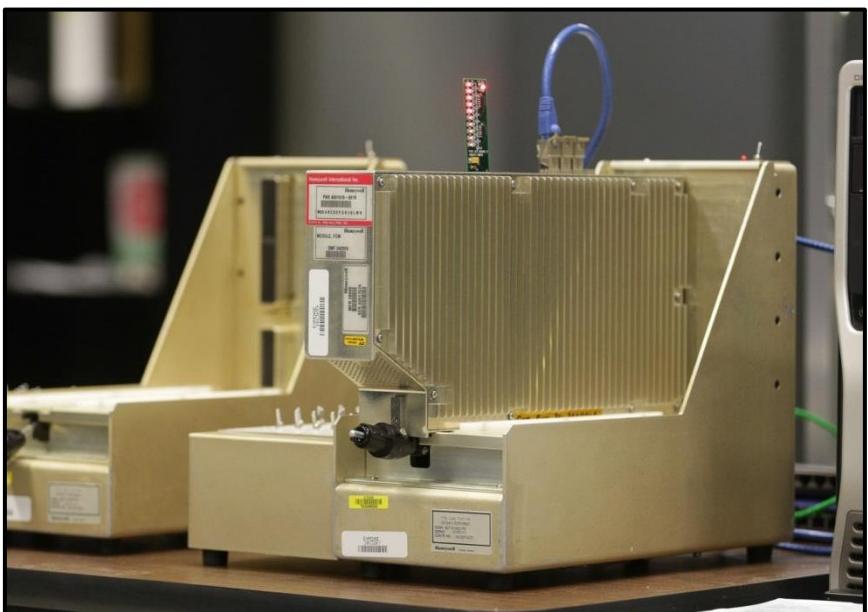
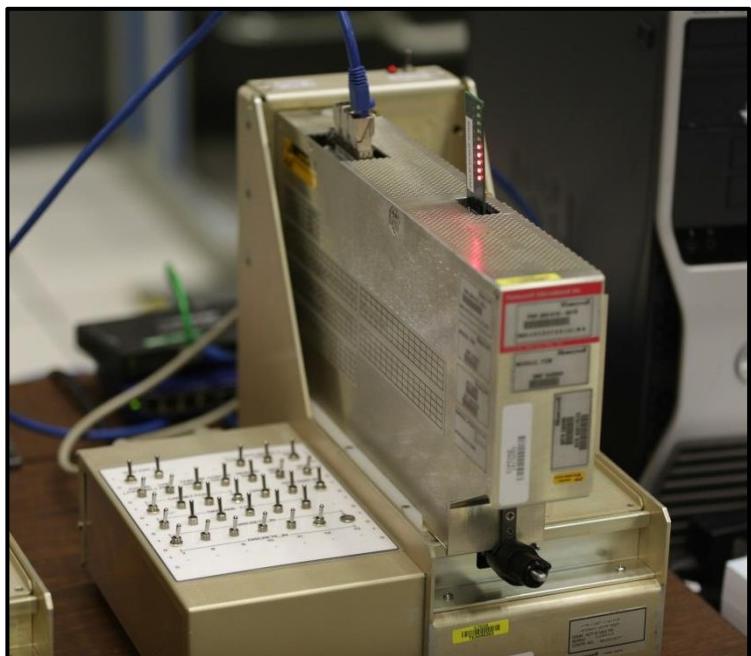
Active and Evolving
- Symmetric & Asymmetric Multicore Development

Progress, Completion FY16

Deferred FY16



# CFS on Partitioned ARINC-653 OS/B787 Class A Product Team

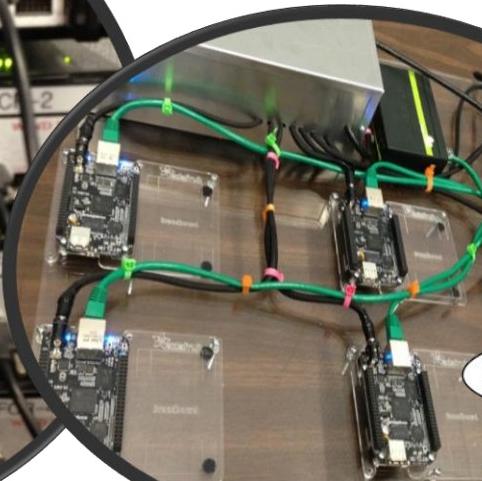




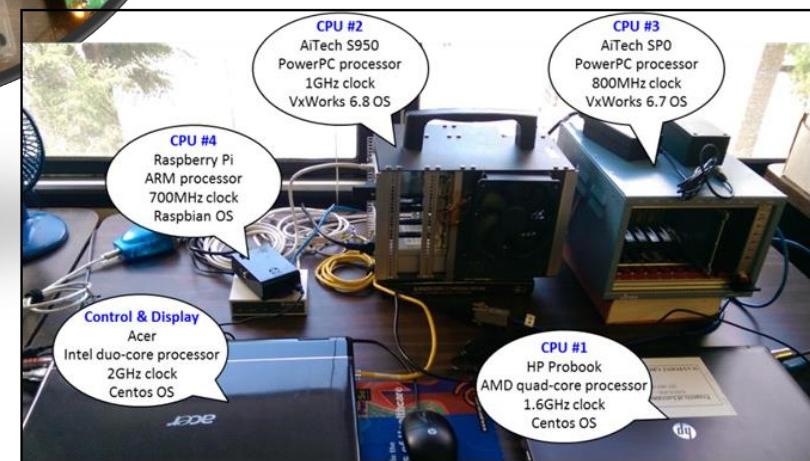
# Synchronization & Voting



Homogeneous Voting:  
Beagle Bone, Rad750, SP0



FY15 Sync & Voting over TTGbE



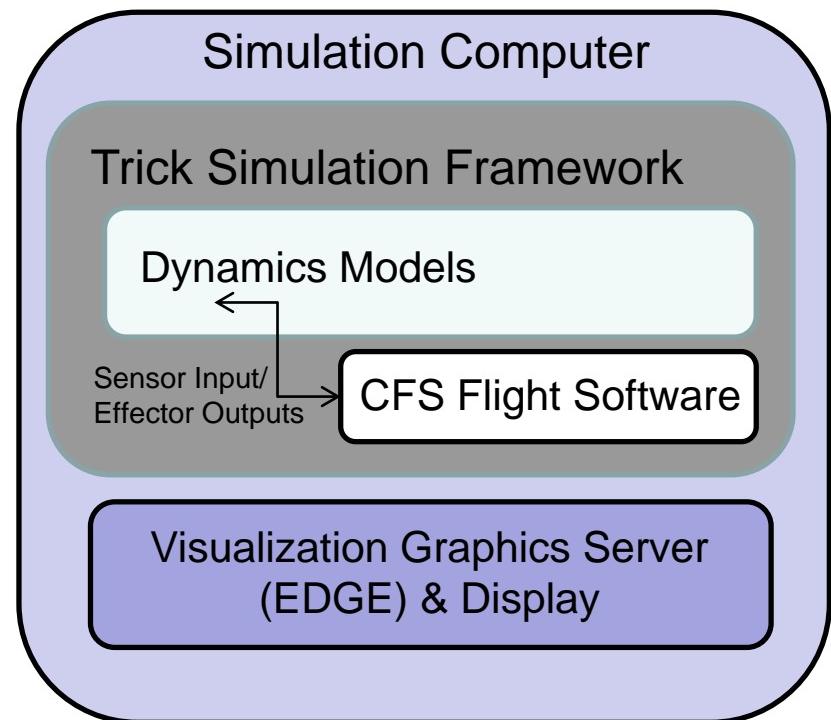
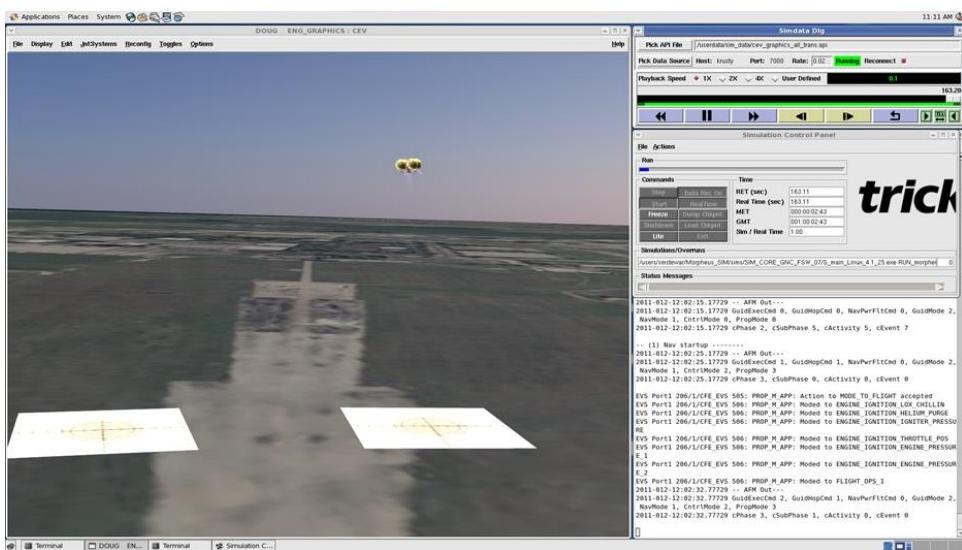
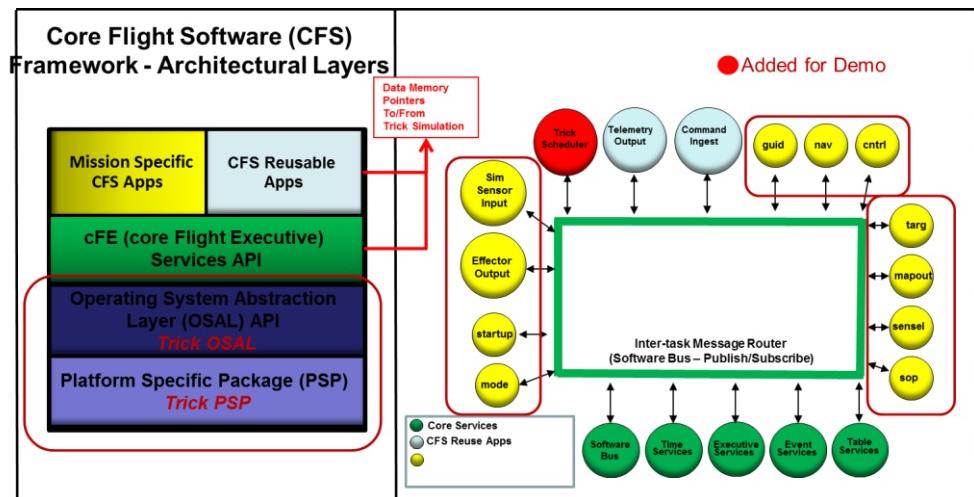
Heterogeneous Voting, Ethernet



# CFS Embedded in Trick Simulation (single executable, Trick scheduler used)

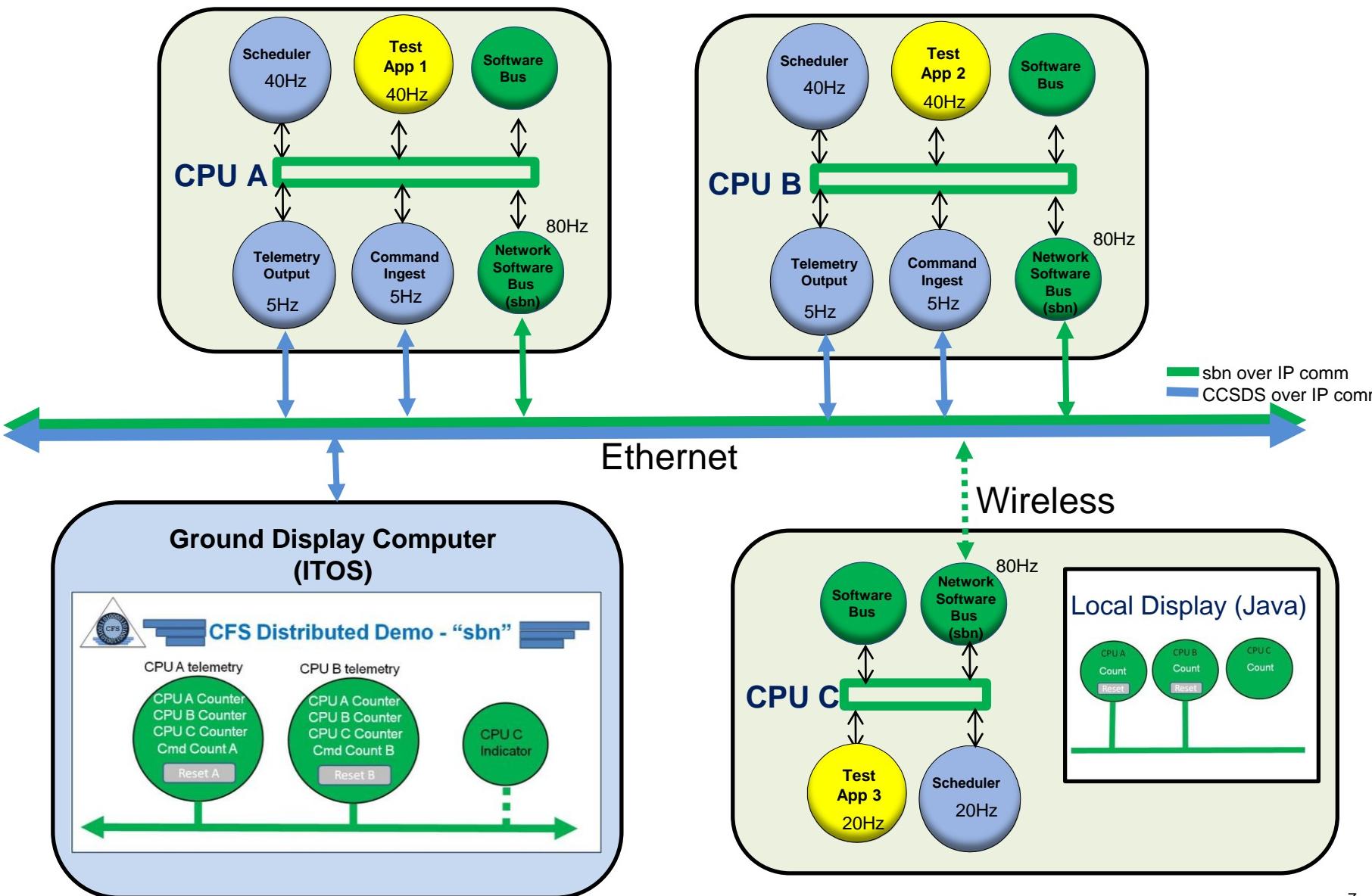


## Morpheus Simulation w/ Flight Software





# Distributed CFS Demo Configuration





# Integrity/Orion Certification Testing Pics



*Verification testing* on  
“SIMICS” hardware  
simulation platform



Kedalion Lab, Houston  
Remote Login



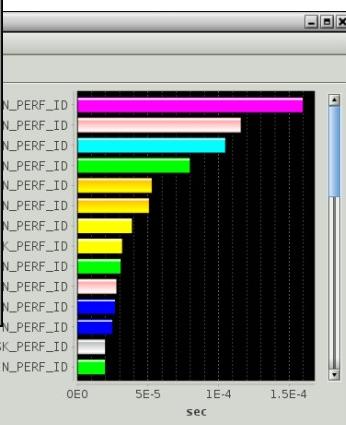
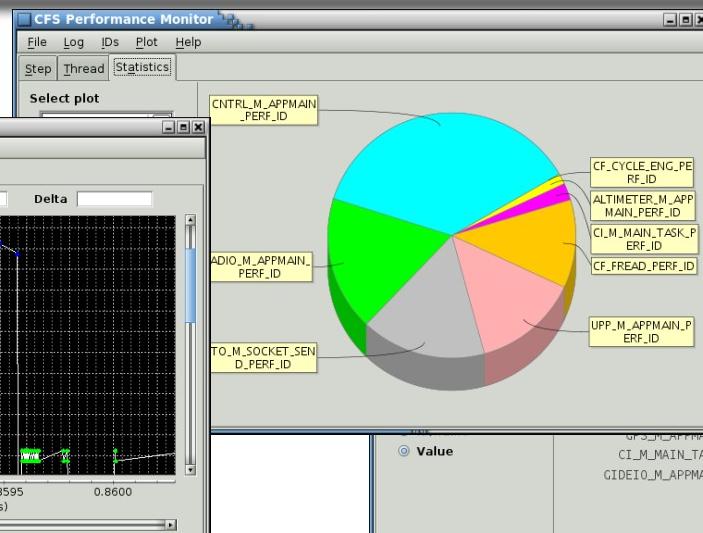
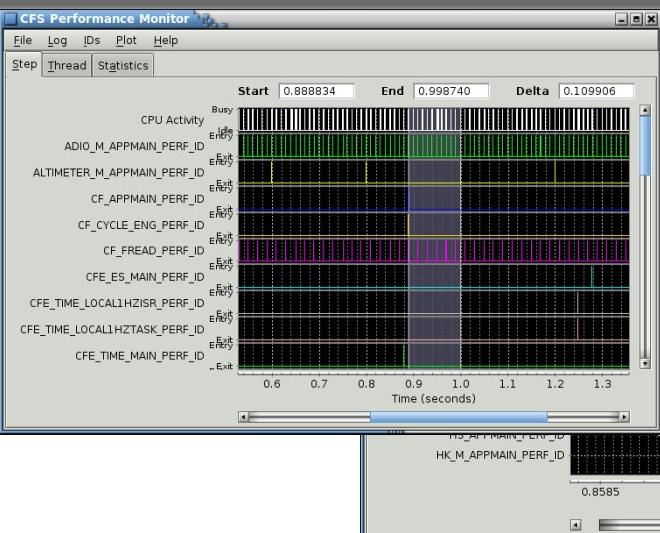
*Validation testing*  
on Orion Self  
Checking Pair EFT-  
1 rig

HOTH Laboratory,  
Lockheed Facility,  
Houston





# Performance Monitoring Tool Screenshots



**Performance ID Editor**

Row	Show	Mask	ID	Name	Color	Freq	Events	Notes
1	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0x000000d0	ADIO_M_APPMAIN_PERF_ID	<span style="color: green;">■</span>	0	330	
2	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0x000000cd	ALTIMETER_M_APPMAIN_PERF_ID	<span style="color: yellow;">■</span>	0	16	
3	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0x00000012	CF_CYCLE_ENG_PERF_ID	<span style="color: blue;">■</span>	0	8	
4	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0x0000000f	CF_FREAD_PERF_ID	<span style="color: orange;">■</span>	0	164	
5	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0x00000021	CI_M_MAIN_TASK_PERF_ID	<span style="color: magenta;">■</span>	0	34	
6	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0x000000c2	CNTRL_M_APPMAIN_PERF_ID	<span style="color: cyan;">■</span>	0	82	
7	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0x00000032	TO_M_SOCKET_SEND_PERF_ID	<span style="color: grey;">■</span>	0	548	

**Buttons:** New, Up, Show All, Color, Clear, Save, Delete, Down, Hide All, Print, Reset, Close

**Log Data: perfLog**

Index	ID	Name	Time Stamp (sec)	Entry/Exit	Seq Err	Overrun (sec)	Notes
263	0x0000000f	CF_FREAD_PERF_ID	0.042382	<span style="color: green;">E</span>			
264	0x8000000f	CF_FREAD_PERF_ID	0.042426	<span style="color: red;">D</span>			
265	0x000000d0	ADIO_M_APPMAIN_PERF_ID	0.042436	<span style="color: green;">E</span>		0.002175	Find out what caused ADIO overrun
266	0x800000d0	ADIO_M_APPMAIN_PERF_ID	0.042461	<span style="color: red;">D</span>			
267	0x000000bf	EMA_IO_M_APPMAIN_PERF_ID	0.042470	<span style="color: green;">E</span>			
268	0x800000bf	EMA_IO_M_APPMAIN_PERF_ID	0.042498	<span style="color: red;">D</span>			
269	0x00000038	DS_APPMAIN_PERF_ID	0.042506	<span style="color: green;">E</span>			

**Buttons:** Print, Close

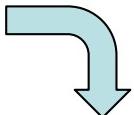
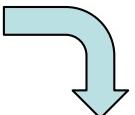
**Log Statistics: perfLog**

ID	Name	Entry Events	Exit Events	Avg Freq (evt/sec)	Time Act (sec)	Time Inact (sec)	Time Act (%)	Time Inact (%)	Min Act (sec)	Max Act (sec)	Min Int (sec)	Max Int (sec)	Min Over (sec)	Max Over (sec)
0x00000025	HK_M_APPMAIN_PERF_ID	1502	1502	915.29	0.001223	1.639792	0.075	99.925	0.000000	0.000094	0.000003	0.012941	n/a	n/a
0x00000038	DS_APPMAIN_PERF_ID	1492	1492	909.19	0.001509	1.639506	0.092	99.908	0.000000	0.000104	0.000001	0.012662	n/a	n/a
0x00000032	TO_M_SOCKET_SEND_PERF_ID	275	275	167.58	0.003817	1.637198	0.233	99.767	0.000005	0.000072	0.000008	0.100094	n/a	n/a
0x000000cf	DIO_M_APPMAIN_PERF_ID	166	166	101.16	0.024685	1.616330	1.504	98.496	0.000051	0.000458	0.000826	0.013286	n/a	n/a
0x000000d7	HDSIF_M_SOCK_PERF_ID	166	166	101.16	0.008247	1.632768	0.503	99.497	0.000001	0.000408	0.000009	0.022701	0.007390	0.012701
0x000000d0	ADIO_M_APPMAIN_PERF_ID	165	165	100.55	0.003445	1.637570	0.210	99.790	0.000009	0.000101	0.006989	0.012714	0.000002	0.002714
0x000000bf	EMA_IO_M_APPMAIN_PERF_ID	165	165	100.55	0.004131	1.636884	0.252	99.748	0.000009	0.000194	0.007197	0.012759	n/a	n/a
0x000000c9	PROP_M_APPMAIN_PERF_ID	165	165	100.55	0.011316	1.629699	0.690	99.310	0.000028	0.000308	0.007014	0.012940	n/a	n/a
Overall		5000	5000	3046.89	0.105892	1.535123	6.453	93.547	0.000000	0.000458	0.000000	1.002590	0.000002	0.002714

**Buttons:** Print, Close



# Mobile Command and Telemetry System



- KSC developed general purpose data integration tool for managing command and telemetry metadata
  - Intended to be generic in nature and applicable to any project using CFS or ITOS
  - Web based interface built with Ruby on Rails
  - Data can be ingested from a variety of formats including flat text files or Excel spreadsheets
  - Imported into PostgreSQL relational database on which a wide variety of queries and reports can be run from MCTS provided GUI screens
  - Currently capable of exporting data directly into ITOS compatible data record format
  - Future enhancements include exporting data to XTCE format files as well as ‘C’ type data structure statements for compiling into CFS application code
  - Demonstration held August 2014

```

/* Define graph for CCSDS processing of test PLIC commands */
Graph gatewayCommands()
{
    connections:
        /* Connect ccdds output to echo input */
        /> PortConnection(p1=cmd_ccdds.output, p2=echo.input)"/
        /* Connect echo output to network transmit input */
        /> PortConnection(p1=echo.output, p2=netTransmitInput)"/
        /* Connect netTransmit output to ccdds input */
        /> PortConnection(p1=netTransmit.output, p2=ccddsInput)"/

    };
    /* Echo commands before they are transmitted */
    ites.graph.EchoComponent.Type(echE)
    /* Transmit command packets over gateway */
    ites.graph.BGPSession.Type(UDP)
    /* Configuration */
    foreign_host [initialValue="XXX.XXX.XXX.XXX"],
    foreign_port [initialValue="12345"],
    associate_on_start [initialValue="1"]
}

};

DiscreteConversion offOnConv{
    Dsc Off [range=<], bgColor=blue, fgColor=white;
    Dsc On [range=>], bgColor=green, fgColor=white;
}

DiscreteConversion unknownOpenConv{
    Dsc Unknown [range=<], bgColor=blue, fgColor=white;
    Dsc Open [range=>], bgColor=green, fgColor=white;
}

DiscreteConversion openClosedConv{
    Dsc Open [range=<], bgColor=blue, fgColor=white;
    Dsc Closed [range=>], bgColor=green, fgColor=white;
}

DiscreteConversion openCloseConv{
    Dsc Open [range=<], bgColor=blue, fgColor=white;
    Dsc Close [range=>], bgColor=green, fgColor=white;
}

DiscreteConversion unknownClosedConv{
    Dsc Unknown [range=<], bgColor=blue, fgColor=white;
    Dsc Close [range=>], bgColor=green, fgColor=white;
}

/* Define graph entry point for PLC commands */
CommandDestination gatewayCommandDestination(
    port=gatewayCommandPortGraph.echo.input
),

```



# Education/Course Idea: CFS on AR Drone Embedded with Trick Controls & Simulation



S T O L (ITOS Release 8.15.0 for i686-RedHat-5.2)

Target IP (CFS) 127.0.0.1

Host IP (ITOS) 127.0.0.1

Enable TLM Output

GUI STOL

ROTWING\_GENERIC\_CMD\_MID

File Edit View Search Terminal Help

AT+PCMD=2420,0,0,0,0,0

AT\*REF=2421,290717696

ended at 105.125000s

Strip Chart

View Actions

Strip Chart

Value

Alt (m)

Abs Psi 114.1

Indoor/Outdoor IN OUT

Shell ON OFF

Init Config

Set Flat Trim

Set goto Ref.

X Pos (Abs) 0.5964

Y Pos (Abs) 0.0026

Z Pos (Abs) -1.015

Roll (deg) 0.00000

Pitch (deg) 0.00000

Batt(0)

ControlState: LANDED

Demo1 Demo2 Time 111

Launch Land

Max Incl.

Roll w. yaw //\\

ON OFF P \\ Max dZ

<< < R HOV R > >> << < Y HOV Y > >>

Set 0.6 Set 0.2 Set 0.2 Set 0.2 Set 0.2 Set 0.2 Set 0.2 Set 0.6

Goto BREAK Cont

Input % Set \\\ Set Rel Abs X Y Z PSI Set \\\ Set Input %

Abs 0.5 0 0 0 0.5 0 0.6 0

Config: 2 -180 -135 -90 -45 0 45 90 135 180 Inf. Cycles

[0] Input Gain 0.2 0.2 0.2 0.002 Rec. 0.2 200 Input Tol

[1] 0.5 0.001 0.001 0.001 Ang 0

[2] Get Set 0.28 0.28 0.28 0.005 Vel 0.02 Get Set

Event Viewer[0]

Windows Options Connection

INFO frame\_sorter 14-083-11:54:12.849: frame\_sorter listening for output\_0

INFO frame\_sorter 14-083-11:54:12.849: frame\_sorter output output\_0 () : 11

INFO frame\_sorter 14-083-11:54:12.866: frame\_sorter created input UDP socket

INFO frame\_sorter 14-083-11:54:12.881: frame\_sorter output output\_0 () : 11

INFO timClient 14-083-11:54:12.894: direct(jsc-er-cfs03,jsc.nasa.gov:388

INFO frame\_sorter 14-083-11:54:12.905: frame\_sorter: accepted output\_0 output

INFO timClient 14-083-11:54:14.656: timClient: global prefix mnem = cfs,

INFO timClient 14-083-11:54:14.667: timClient: global prefix = decom,cfs

INFO timClient 14-083-11:54:14.667: timClient: global prefix = decom,cfs

Value

sim.ardroneSim.state.cgPos[0] sim.ardroneSim.state.cgPos[2]

Domain Axis All Strip 30.0 Fixed

Display Lines Points Show Legend

Variables Add sim.ardroneSim.nav.eulerRates[0] Remove sim.ardroneSim.state.cgPos[0] Domain Axis: Simulation Time (seconds)

Value

sim.ardroneSim.state.bodyWindVel[0] sim.ardroneSim.state.cgVel[0]

Domain Axis All Strip 30.0 Fixed

Display Lines Points Show Legend

Variables Add sim.ardroneSim.nav.eulerRates[0] Remove sim.ardroneSim.state.bodyWindVel[0] Domain Axis: Simulation Time (seconds)

Value

sim.ardroneSim.state.cgPos[0] sim.ardroneSim.state.cgPos[2]

Domain Axis All Strip 30.0 Fixed

Display Lines Points Show Legend

Variables Add sim.ardroneSim.nav.eulerRates[0] Remove sim.ardroneSim.state.cgPos[0] Domain Axis: Simulation Time (seconds)

Value

sim.ardroneSim.state.dragForce[0]

Domain Axis All Strip 30.0 Fixed

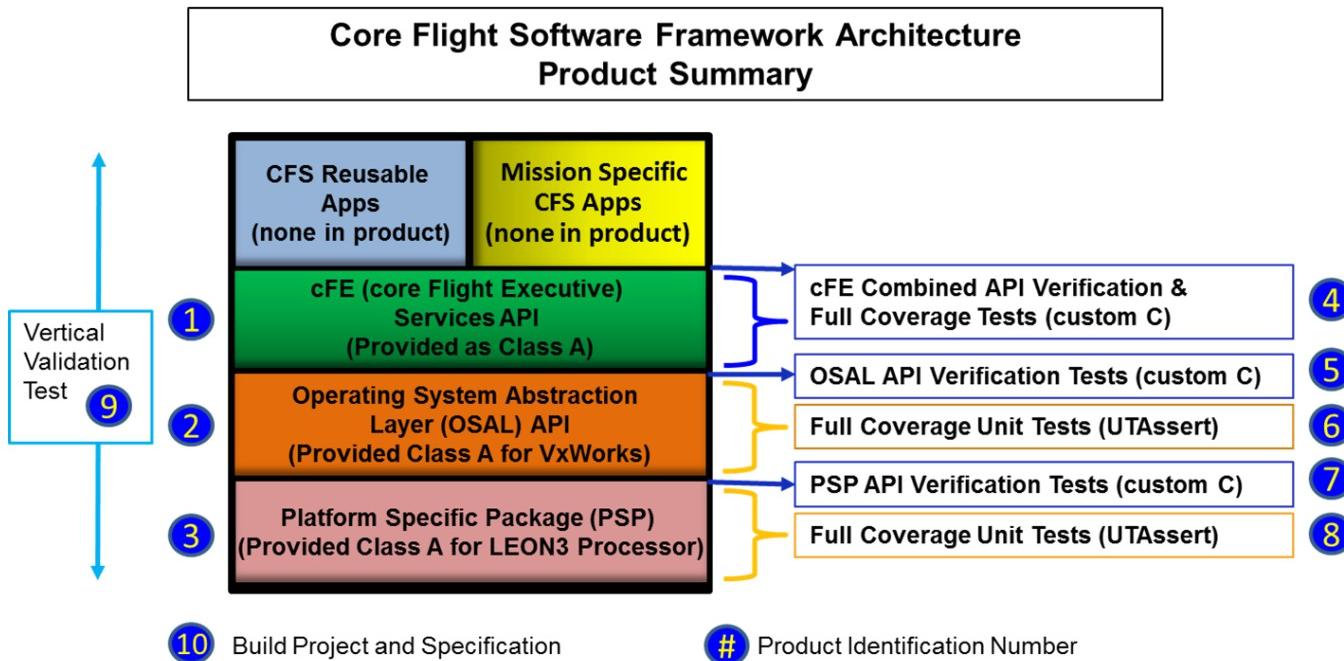
Display Lines Points Show Legend

Variables Add sim.ardroneSim.nav.eulerRates[0] Remove sim.ardroneSim.state.dragForce[0] Domain Axis: Simulation Time (seconds)

2014 MASTERS 3/3



# CFS VxWorks/LEON3 Class A Product/Test Suite Summary



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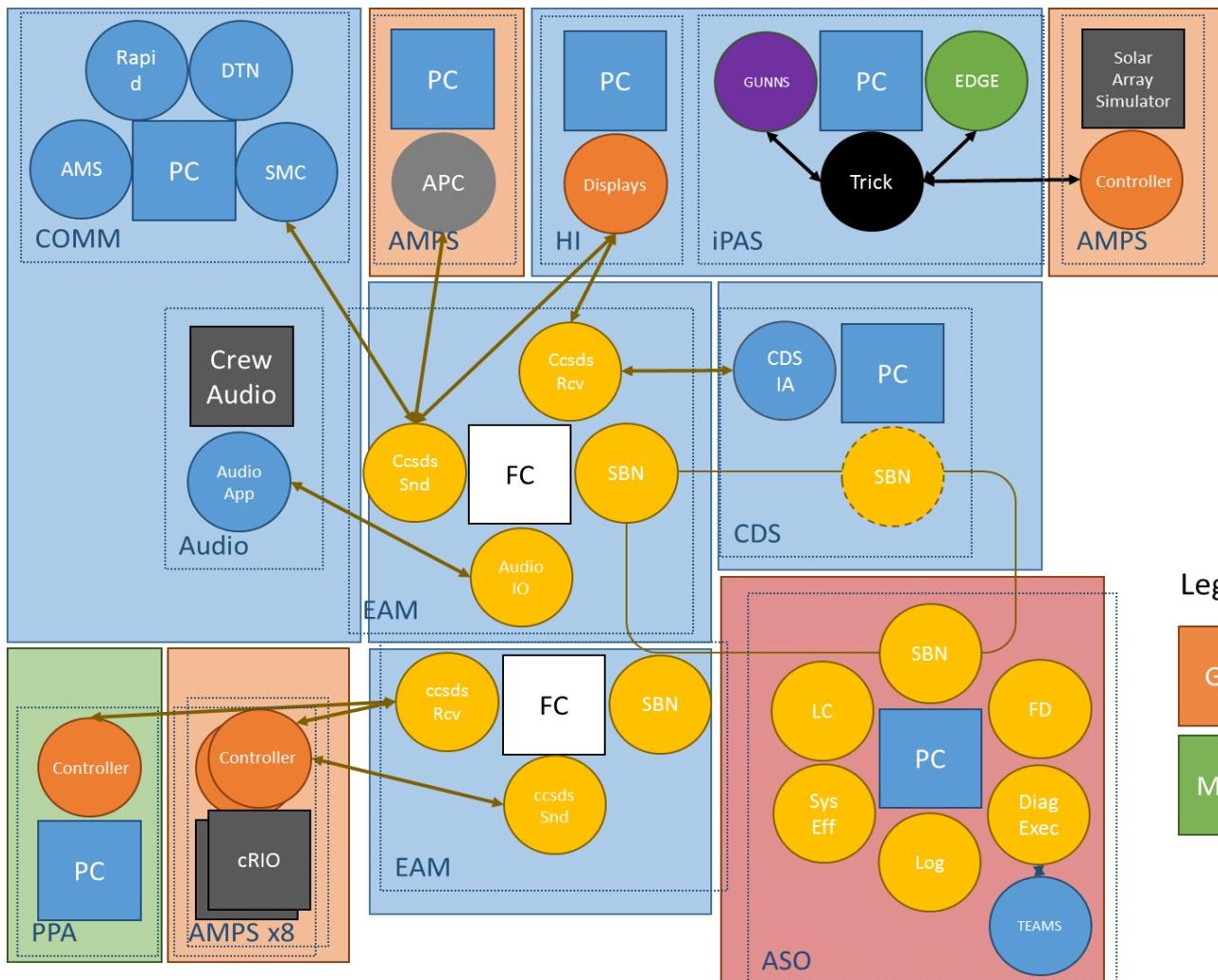
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# AES Project Integration with CFS/sbn (FY15) (Habitat DRM)



- AMPS – AES Modular Power System
- AMS – Asynchronous Message Service
- APC – Autonomous Power Controller
- ARC – Ames Research Center
- ASO – Autonomous System Operations
- ccsdsRcv – CFS user app
- ccsdsSnd – CFS user app
- CDS – Cascade Distillation System
- COMM – Communications System
- cRIO – compact reconfigurable I/O
- DiagExec – Diagnoser Executive app
- DTN – Disruption Tolerant Networking
- EAM – Exploration Augmentation Module
- FC – flight computer
- FD – Failure Detector app
- GUNNS – General Use Nodal Network Solver
- GRC – Glenn Research Center
- HI – Human Interfaces
- IA – interface app
- iPAS – integrated Power, Avionics, & Software
- JSC – Johnson Space Center
- LC – Limit Checker app

## Legend



- MSFC – Marshall Space Flight Center
- PC – personal computer
- PPA – Plasma Pyrolysis Assembly
- RAPID – Robotic control standard
- SBN – Software Bus Network app
- SM&C – Space Craft Monitoring and Control
- SysEff – System Effects app
- TEAMS – Real-time diagnostics and reasoner



# AES AMO Project: Vehicle Systems Automation

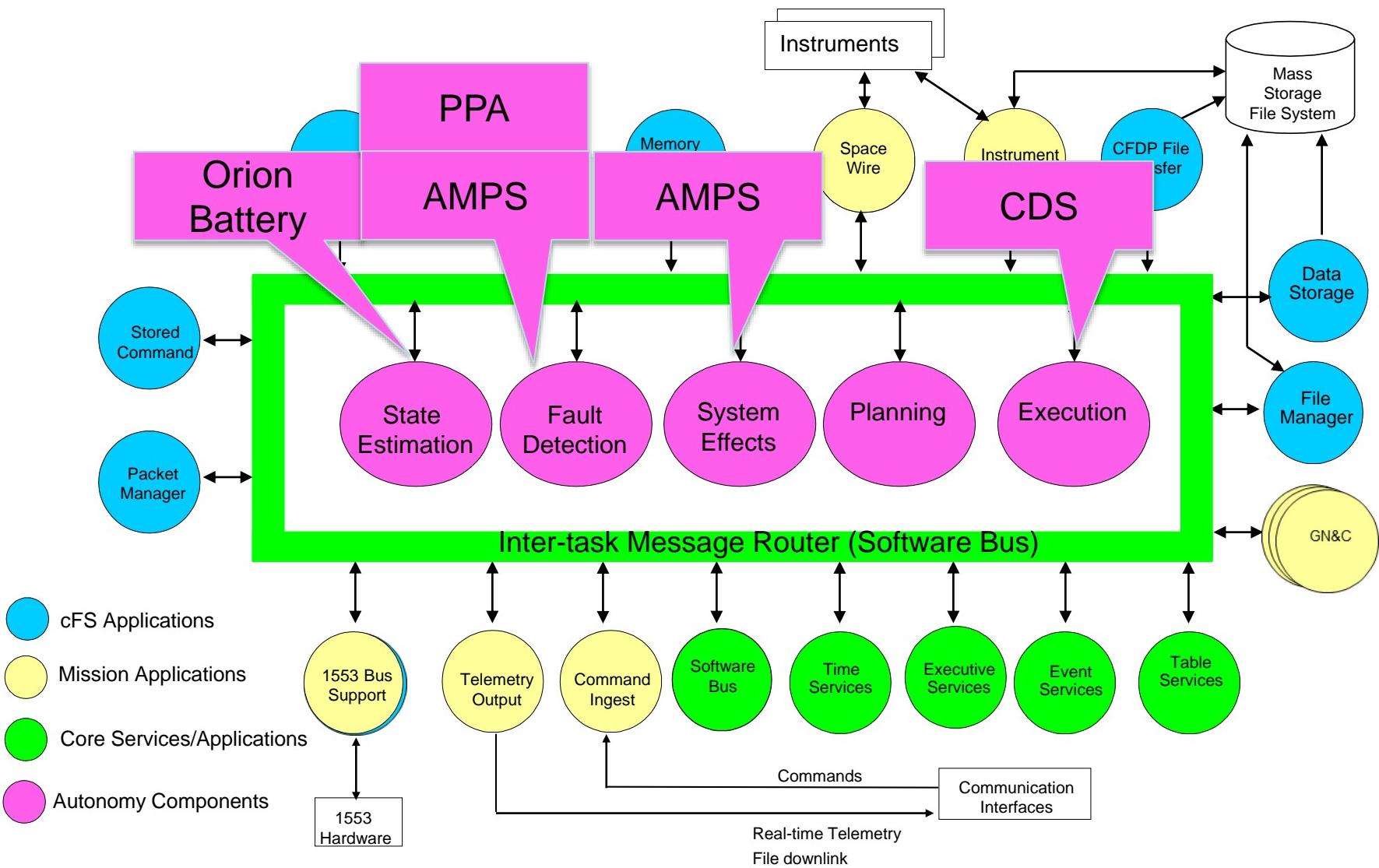
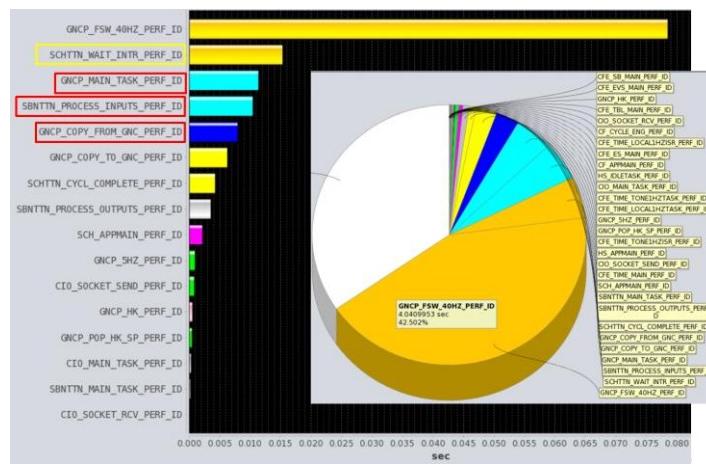
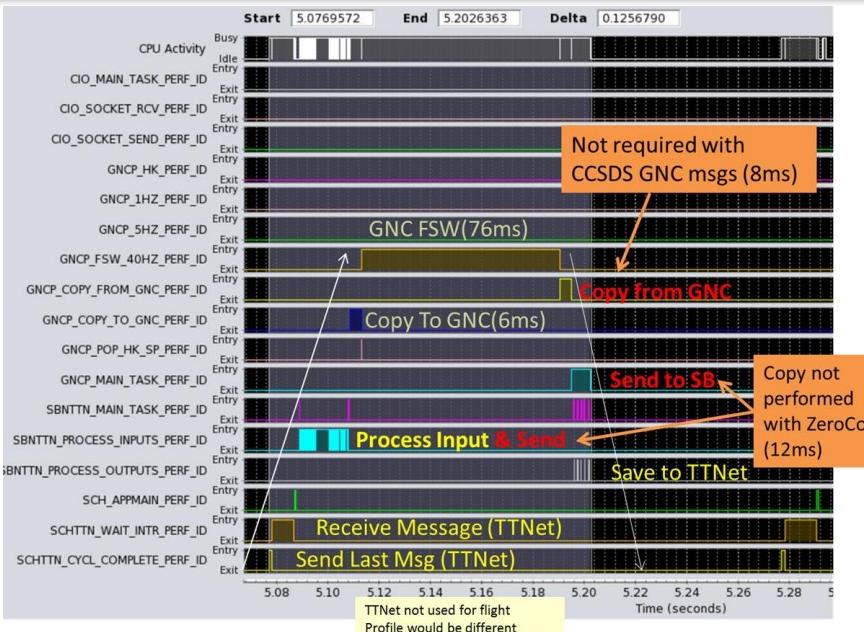
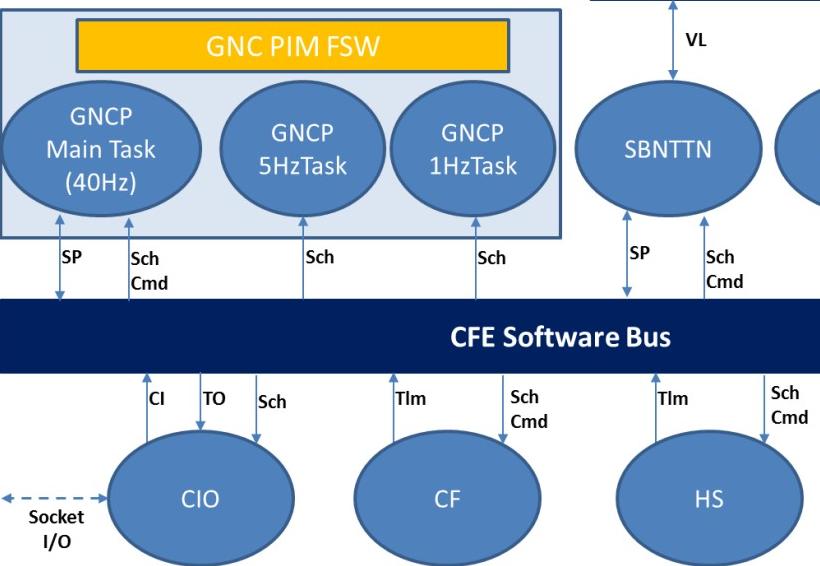
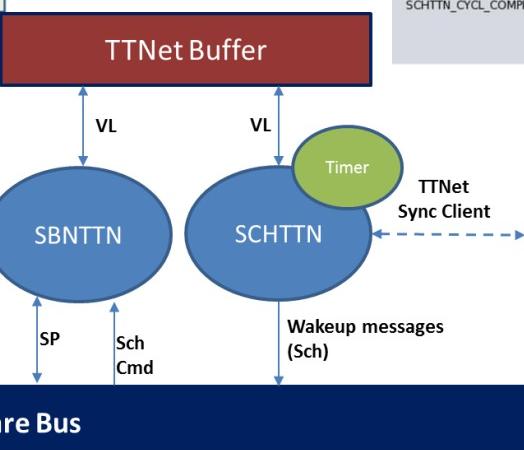
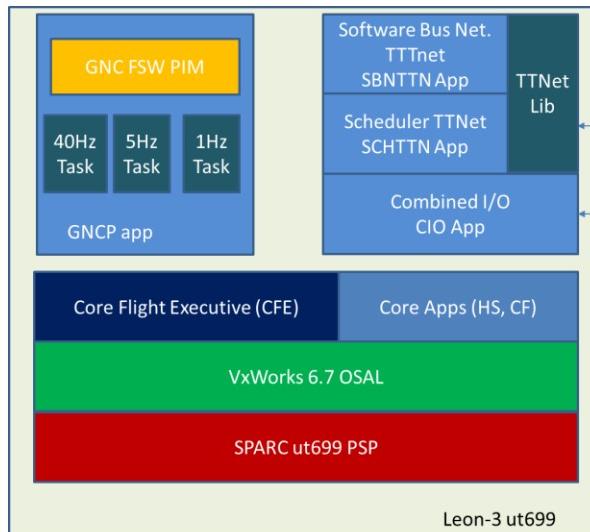


Chart obtained from FY15 AES AMO End of Year Review / Jeremy Frank / ARC



# Orion Backup Computer Proof-of-Concept Architecture (EFT-1 Flight Code under CFS on LEON3 Processor)



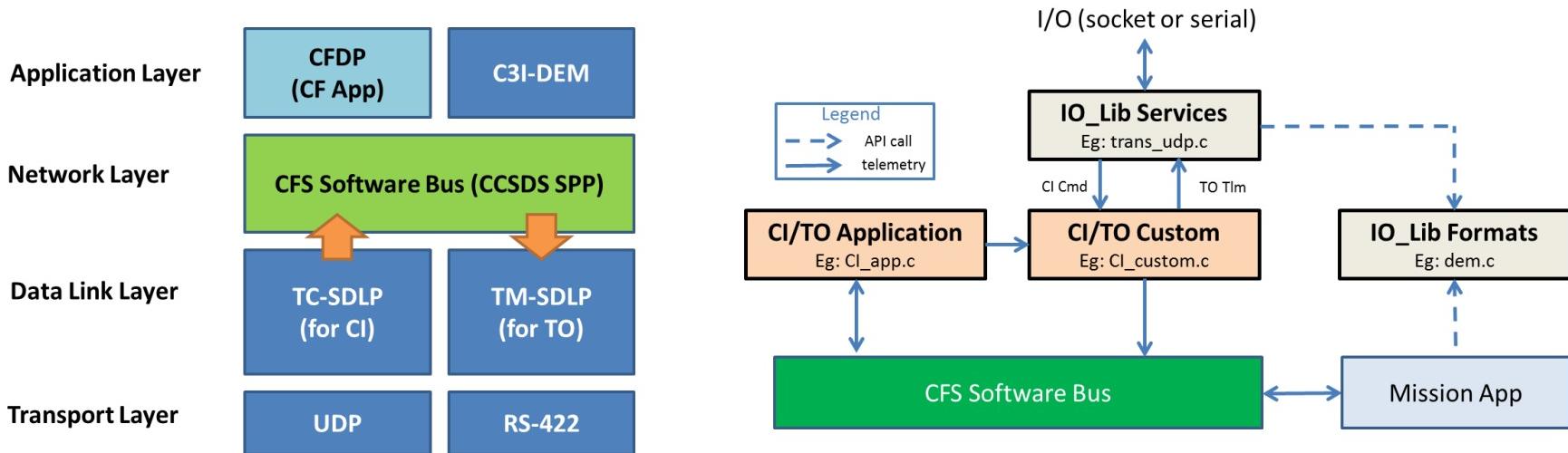


# Generic TO/CI Apps with C3I Interface



## ◆ Product Summary

- New applications to handle Command Inputs / Telemetry Outputs
- Designed such that it can be easily expanded and customized for specific mission needs through a library suite called IO\_LIB.
- Multiple channels supported, reconfigurable through CFS tables
- Supports communication over UDP and RS-422
- CCSDS Space-Data Link Protocols: TM-SDL, TC-SDL, COP-1
- Integration with the File Transfer Application (CF) for CFDP file transfers



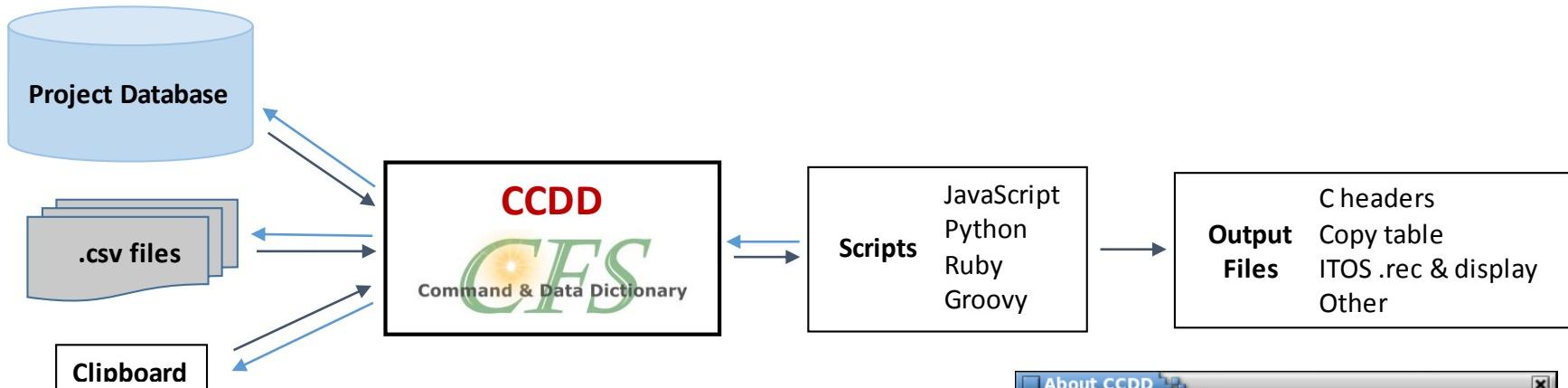


# CFS Command & Data Dictionary Tool (CCDD)



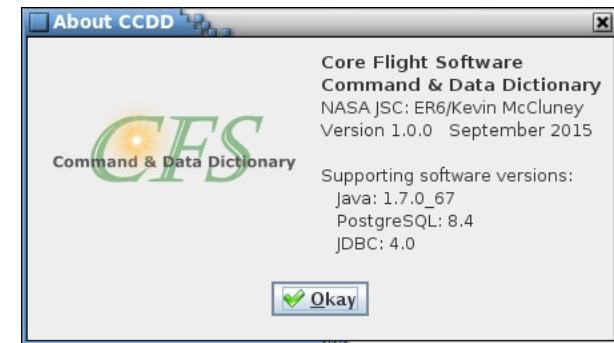
## ◆ Product Summary

- Provides a means for managing CFS and CFS application variable structure and command message information in a PostgreSQL database
- Data can be accessed by user-defined scripts using built-in access functions; e.g., to create output files (C headers, HK copy table, etc.)



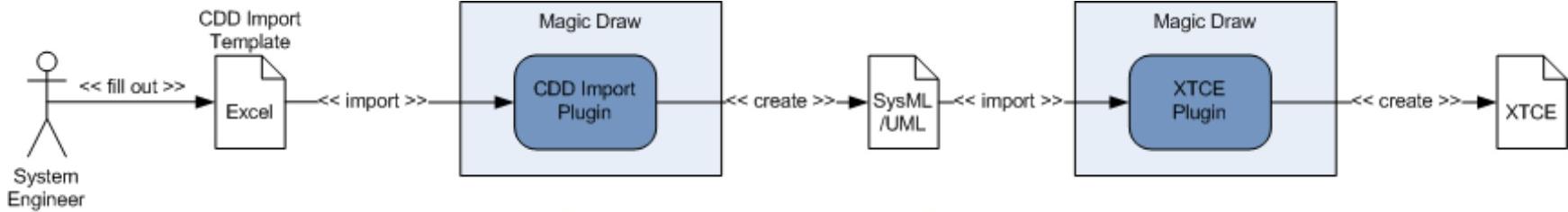
## ◆ Demo Description

- Basic application functionality
  - Project creation
  - Data entry
  - Data customization
  - Script access





# Collaboration Manager Tool

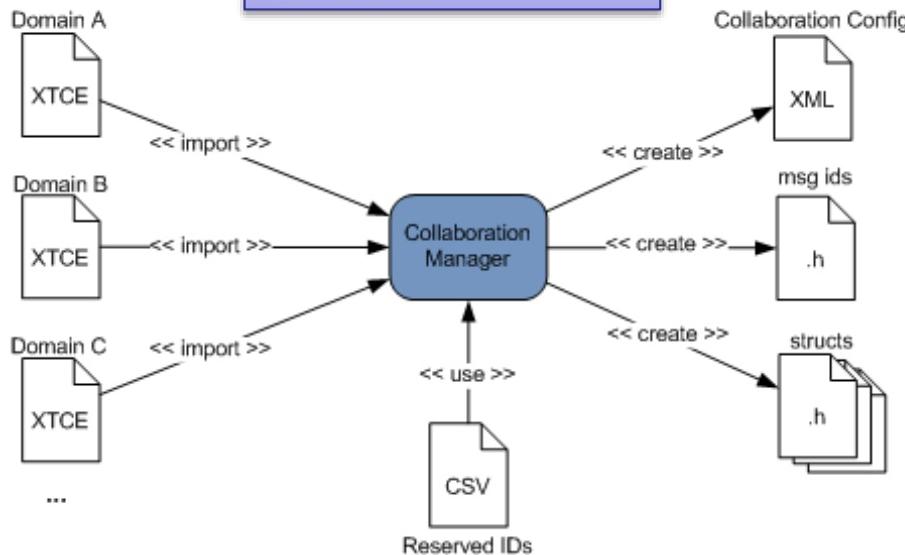


System Engineer describes system command and telemetry lists

System representation  
SysML model is generated

XTCE files describing system representation is generated

XTCE files used to create other product files



Message IDs pulled from available user app pool



# CFS Supported Platforms

## (non-exhaustive)



Platform	OS	Project	Status / Notes
RAD750	vxWorks 6.4	LRO,RBSP, GPM	Project tested.
RAD750	RTEMS 4.10	ICESat-2/ATLAS	Early in instrument test program
Rad Hard Coldfire (5208)	RTEMS 4.10	MMS	Project tested.
LEON3	RTEMS 4.10	Solar Probe Plus	In Development for SPP mission
MCP750 PPC	vxWorks 6.4	cFE/CFS Project	Tested. Used as baseline CFS development platform.
PC / x86	Linux	n/a	Not formally tested. Used by JSC.
Coldfire MCF5235 board	RTEMS 4.10	n/a	Not formally tested. Used for RTEMS Development, and MMS board.
LEON3 – generic – (simulator, multiple COTS boards )	RTEMS 4.10	n/a	Not tested. Not in CFS CM. Used for LEON3 development. Can be used on LEON3 Simulator.
Coldfire Simulator (qemu 68k )	RTEMS 4.10	n/a	Not formally tested. Used for OSAL / cFE development
TILER	Linux	Maestro IRAD (FY12)	Not formally tested. Compatible with Desktop PC linux version.
MCP750 PPC	vxWorks 6.x	Memory Protection IRAD (FY11)	Adds memory protection to standard cFE. Not formally tested. Not integrated with cFE repository.
PC x86	Linux	Multi-Core IRAD (FY12)	Adds multi-core CPU capability to cFE. Not formally tested. Not integrated with cFE repository.
Leon3	PikeOS	Virtualization IRAD (FY12)	Adds ability to run in partitioned OS. Prototype. Not integrated with cFE repository.

Platform	OS	Project	Status / Notes
Aitech S950 (PPC750FX)	vxWorks 6.7	Morpheus	In JSC CM. Integration tested on real Morpheus Vehicle hardware. Flown on Morpheus test vehicle.
RTD pc386-IDAN, PC104, Pentium M	RTEMS 4.10	ISS Downmass/Micro Capsule	In JSC CM. Integration tested on real Micro Capsule hardware.
RTD IDAN Core 2 Duo	SUSE Linux	DoD Payloads Office STPSat-4	In development. Used only for C&DH, payload data handling, data recording(ds), file downlink (CFDP), extensive onboard autonomy (sc)
Acro Virtex 5	VxWorks 6.9	AEMU	In development.
Space Micro Proton P400k	VxWorks SMP 6.8	MMSEV, AAE	In JSC CM. MMSEV FY13.
Maxwell SCS750	VxWorks 6.9 RTEMS 4.10	EAM, AAE	In JSC CM. EAM/DSH
787FCM	Integrity ARINC	AES CFS	In JSC CM. Class A cert. ARINC653 cFE, OSAL.
OrionSCP	Integrity ARINC	AES CFS	In JSC CM ARINC653 cFE, OSAL.
750FCR	VxWorks ARINC 6.8	AES CFS	In JSC CM FTSS SW fault containment with a voting quad architecture.
Trick (simulation environment)	Linux	AES CFS	In JSC CM RPM
LEON3	VxWorks 6.7	Orion BFS	In JSC CM. Class A cert. BFS prototype. Currently in ic-sgd-dev-trac-10-merge branch, release Dec 2015
AiTech SP0	VxWorks 6.9	AES Voting, RPM?, AA2?	Currently in ic-sgd-dev-trac-10-merge branch, release Dec 2015
BeagleBone, Raspberry Pi	Linux, Raspbian Linux	Misc, voting, outreach/drone	



# AES CFS FY16 Tasks/Tentative



Task Name	Focus, activities, description
<b>Product Line</b>	Community Product Line: CCB, product evolution, changes, merges, open source releases
<b>AES Project Deployment</b>	Continue deployment of CFS products in "field" of other AES projects and/or users Continue migration of AES project apps to CFS
<b>Multicore</b>	<ul style="list-style-type: none"><li>- Get Symmetric Multicore Processing (SMP) OSALs working on LEON4 &amp; Tilera 36</li><li>- Get Asymmetric Multicore Processing (AMP) environment set up on LEON4 &amp; Tilera 36</li><li>- Perform SMP Analysis<ul style="list-style-type: none"><li>- load balancing with processor intensive apps &amp; characterize performance</li></ul></li><li>- Perform AMP Analysis –<ul style="list-style-type: none"><li>- Investigate multiple OS's/Hypervisor on different cores</li><li>- different applications on different cores,</li><li>- sbn between cores</li><li>- put synch/voting on selected cores</li><li>- Put autonomy apps on cores &amp; measure performance</li></ul></li></ul>
<b>Generic TO/CI</b>	<ul style="list-style-type: none"><li>- Enhancements to support outstanding requirements/design items approved for implementation</li><li>- Enhancements in support of Orion DEM updates</li></ul>
<b>Sync/Voting</b>	<ul style="list-style-type: none"><li>- Apply to real-world application (AA-2 GNC)</li><li>- Study, stress &amp; characterize performance on TTGbE with real applications using data</li></ul>
<b>Xenomai OSALs</b>	<ul style="list-style-type: none"><li>- Get default-skin Xenomai version of CFS running on UEIPAC platform<ul style="list-style-type: none"><li>- study performance with sample apps &amp; timing tests</li><li>- modify OSAL if necessary, get new PSP working</li></ul></li><li>- Develop partitioned version of Xenomai for CFS<ul style="list-style-type: none"><li>- Utilize test applications on partitions &amp; study performance</li></ul></li></ul>
<b>sbn</b>	<ul style="list-style-type: none"><li>- Acquire latest &amp; stress test</li><li>- Merge latest sbn into product line</li><li>- Stress test performance with multiple deployments on multiple machines and higher speeds</li><li>- Enhance as Needed supporting multiple AES distributed projects</li></ul>
<b>CCDD</b>	<ul style="list-style-type: none"><li>- Complete development, adding XML, XTCE &amp; clean up</li><li>- Possible add EDS</li><li>- Deploy to uses &amp; provide updates/maintenance/improvements as needed</li></ul>
<b>Education/Outreach</b>	<ul style="list-style-type: none"><li>- Complete deployment package for universities</li></ul>



# Symmetric Multiprocessing CFS Development



- ◆ Symmetric Multiprocessing (SMP) Support
  - Description
    - Provide a generic SMP Operating System Abstraction Layer (OSAL) supporting multi-core processor architectures
  - Accomplishments
    - Prototype implementation of CFS on dual core Space Micro Proton board and VxWorks SMP complete
      - Apps can be allocated to specific cores to deterministically balance processing load or to improve performance of certain apps
  - Remaining Work (FY15)
    - Implement on SPARC LEON 4 quad-core, Tilera 36-core
    - Merge SMP support modifications into mainline CFS

Proton



LEON4 quad-core

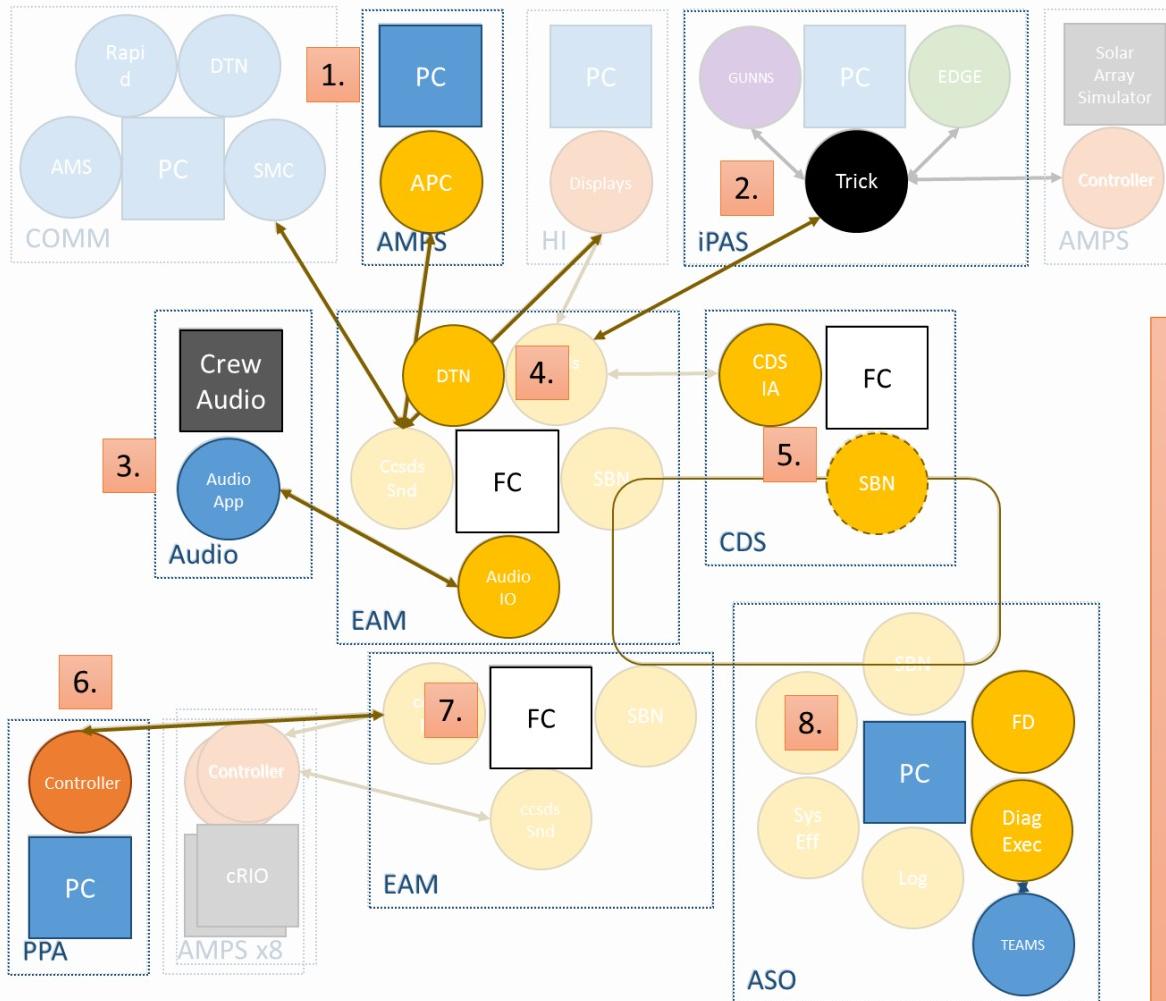


Tilera 36-core





# FY16 Software development plan



## Planned maturity for FY16

1. Mature AMPS Autonomous Power Controller (APC)
2. Enable telemetry from TRICK integrated vehicle systems simulation
3. Develop CFS controller app for onboard crew audio system
4. Deploy Disruption Tolerant Networking (DTN) capability onto flight computer platform
5. Mature embedded controller of Cascade Distiller System (CDS)
6. Expand CFS/LabVIEW interface of Plasma Pyrolysis Assembly (PPA)
7. Deploy CFS builds to path-to-flight model avionics
8. Expand fault detection models within Autonomous Systems Operations (ASO) suite



# Projects Use of CFS at JSC

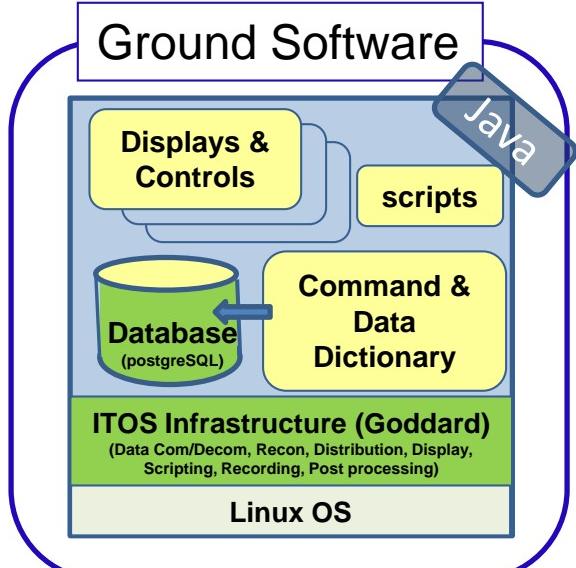
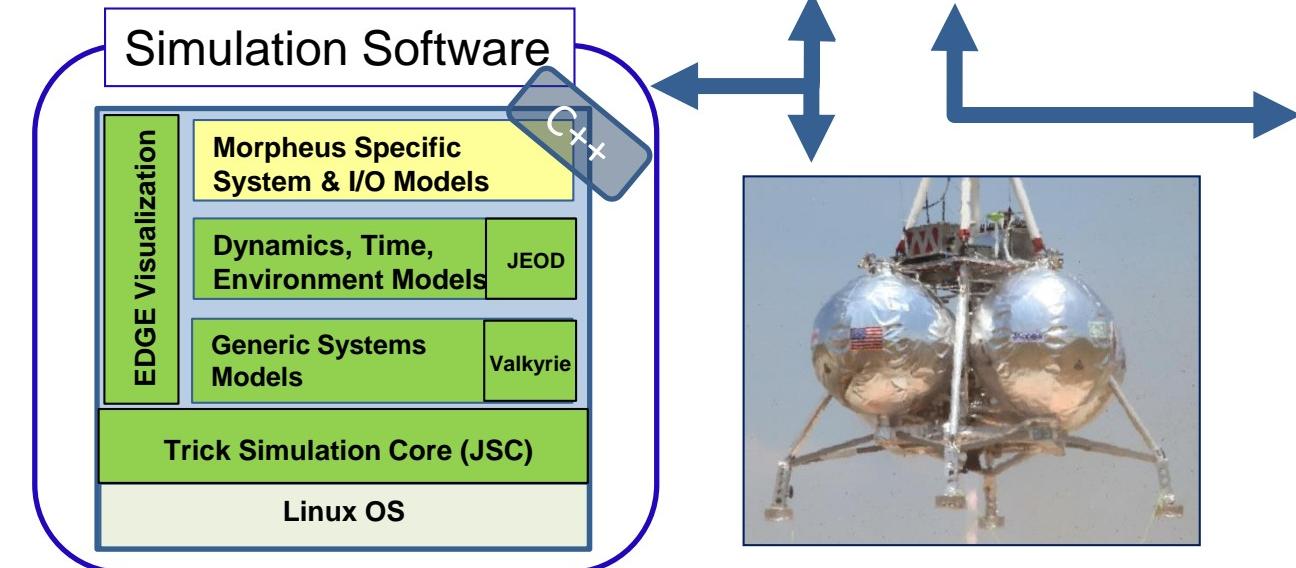
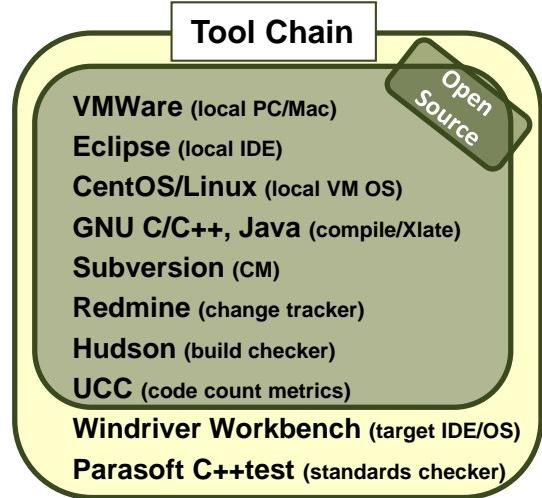
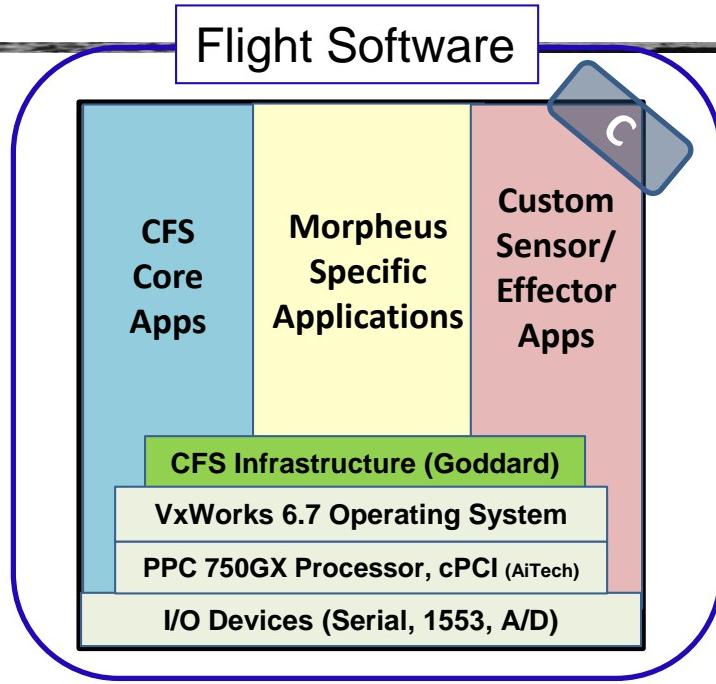


- ◆ Morpheus Lander (VxWorks, Aitech S950)
- ◆ AES CFS, Avionics & Software Projects (already discussed)
- ◆ MMSEV (VxWorks, S950)
- ◆ Downmass MicroCapsule (RTEMS, Pentium)
- ◆ Other AES Projects:
  - Advanced IMU Space Suit (Linux, Vertex 5 microblaze)
  - ASO, DTN, CDS, AMPS...
- ◆ DoD Payloads Office STPSat-4 Deployed Payload (SUSE Linux, RTD IDAN Core 2 Duo)\*
- ◆ Orion Vision Processing Unit (VPU)\*
  - Includes Backup Flight System (BFS) (VxWorks, LEON3)
- ◆ Orion Video Processing Unit (Linux, I5)\*
- ◆ Orion AA-2 Flight Experiment (VxWorks, TBD)\*

\* Flight Projects in Development

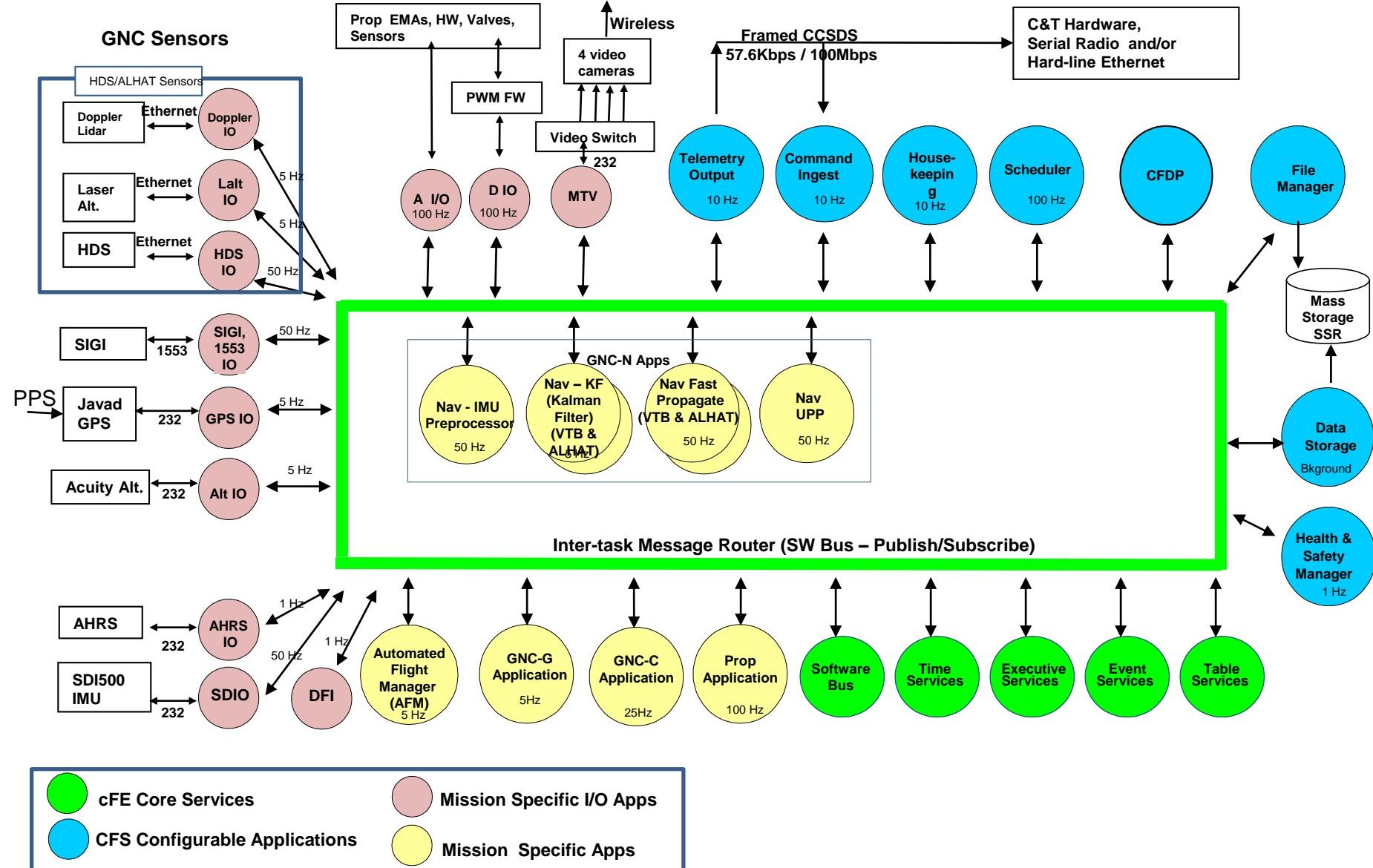


# Morpheus Software Components



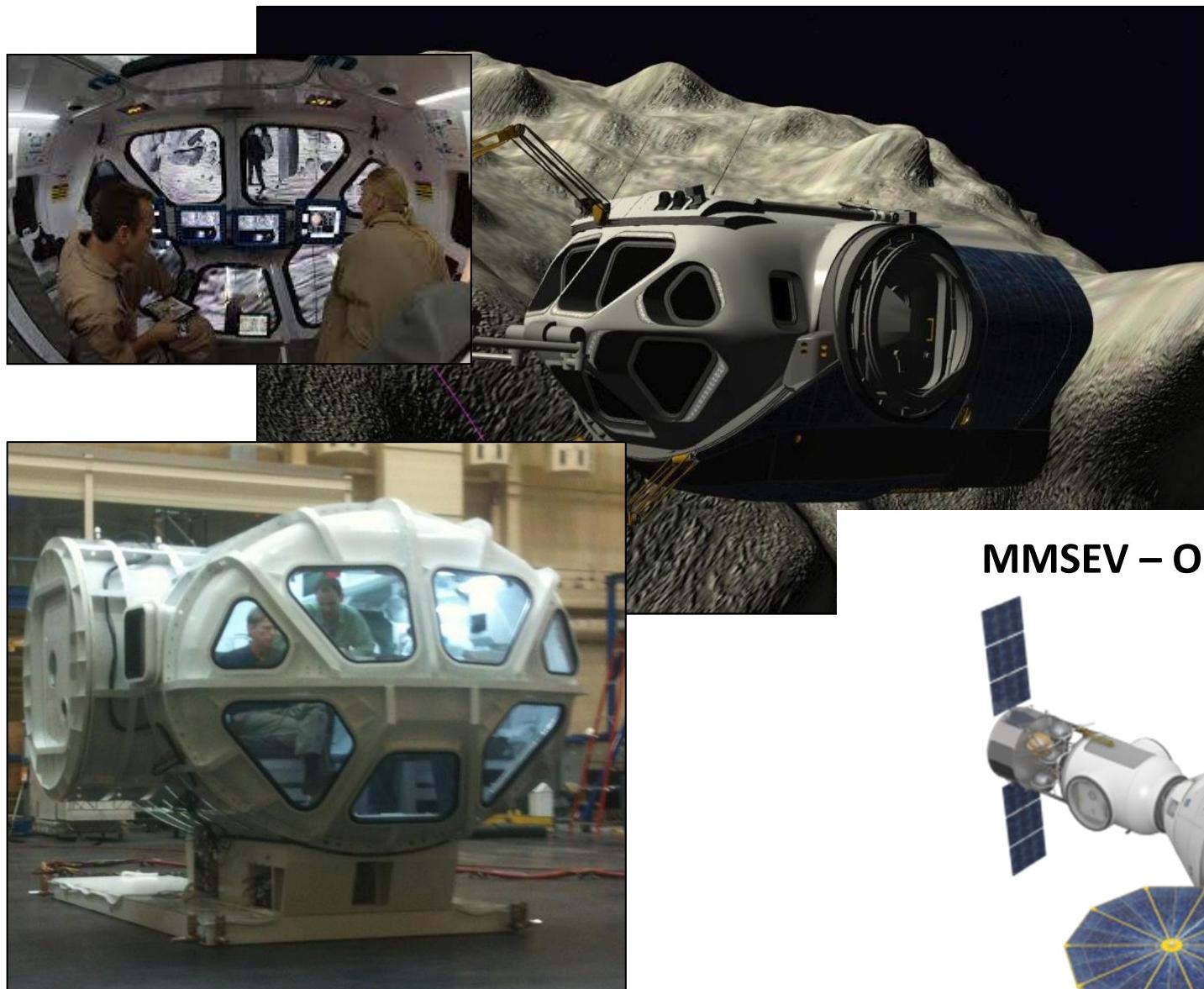


# Morpheus Flight Software Architecture





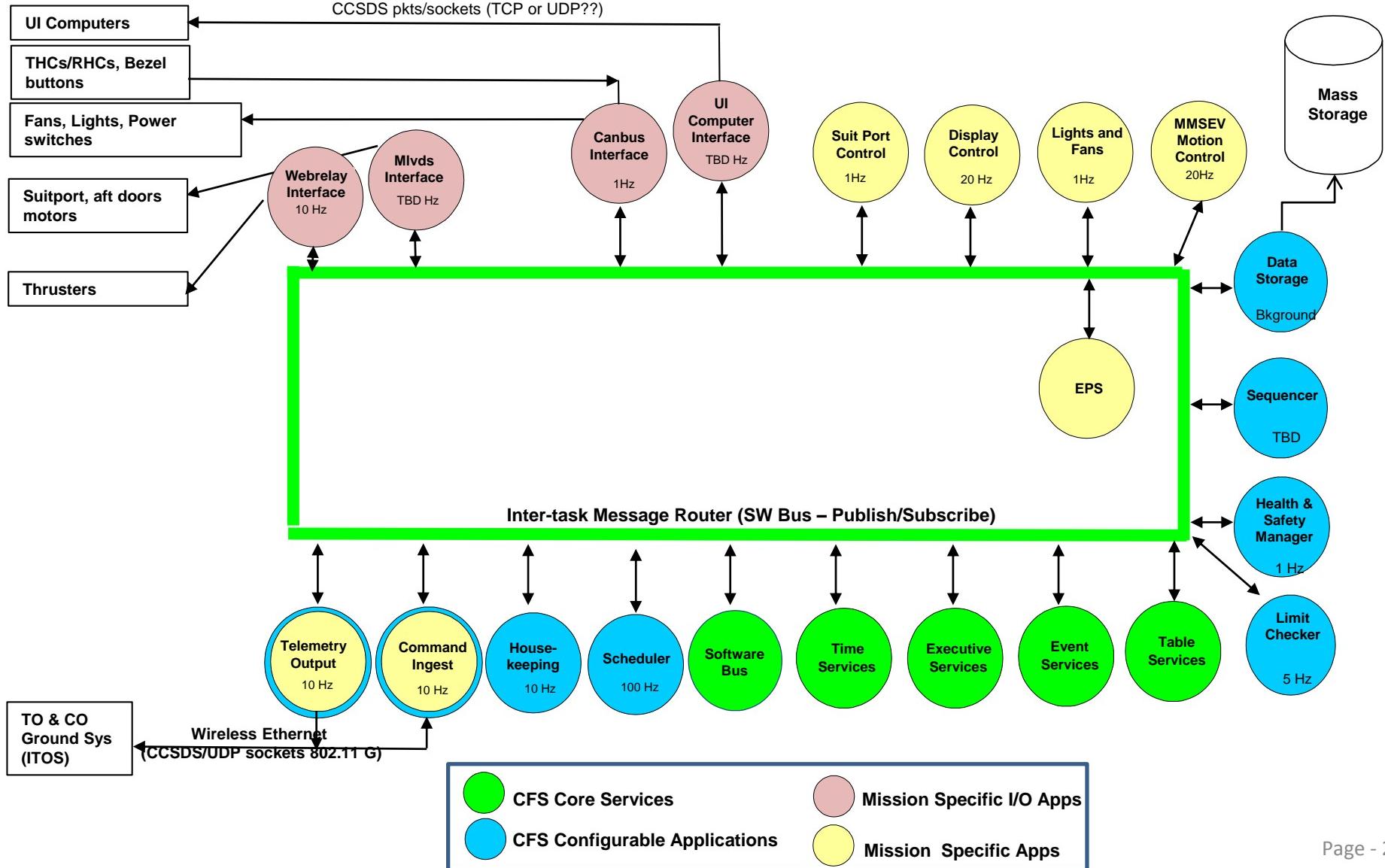
# MMSEV



**MMSEV – Orion Augmentation Module (OAM)**

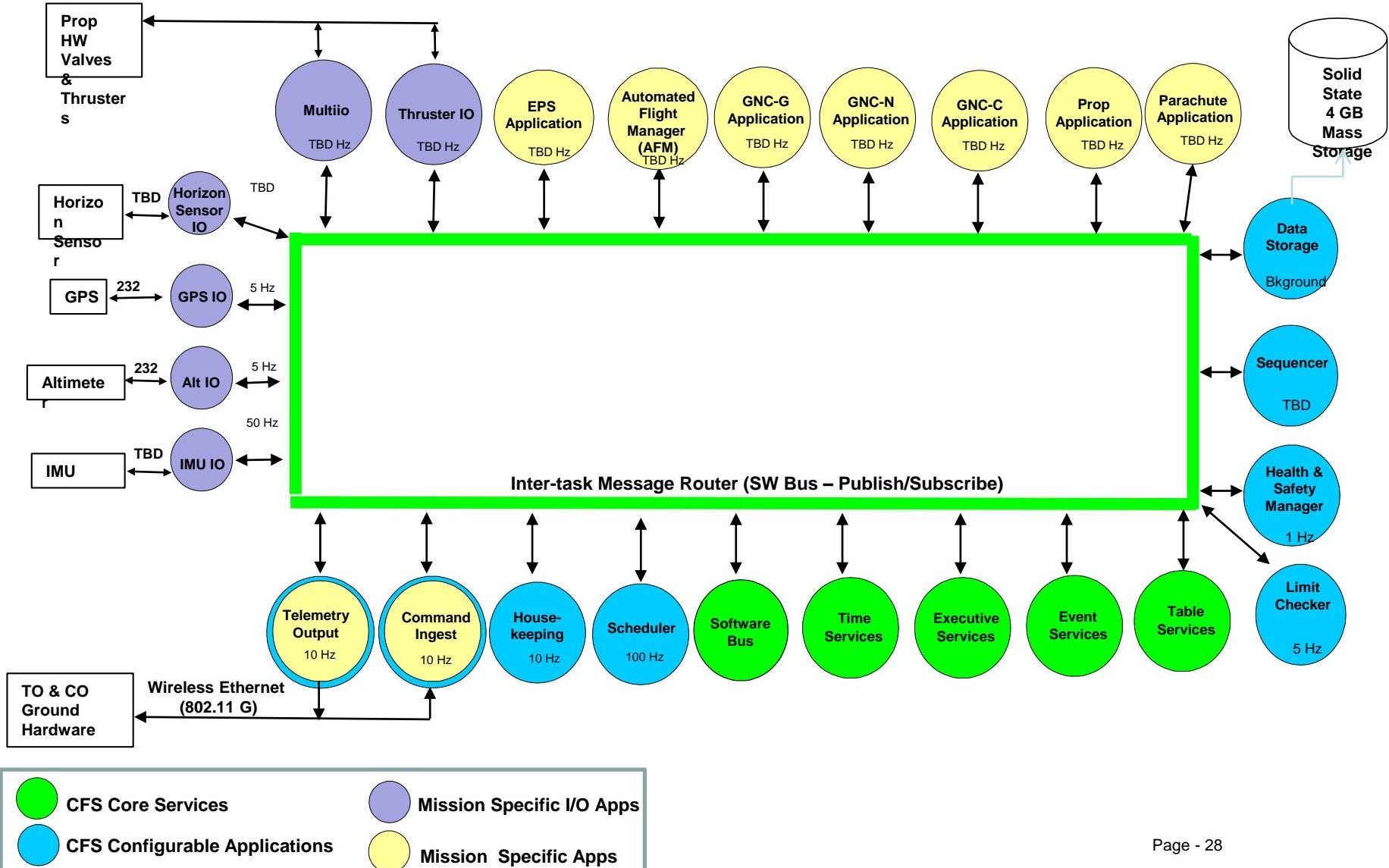


# MMSEV CFS Architecture



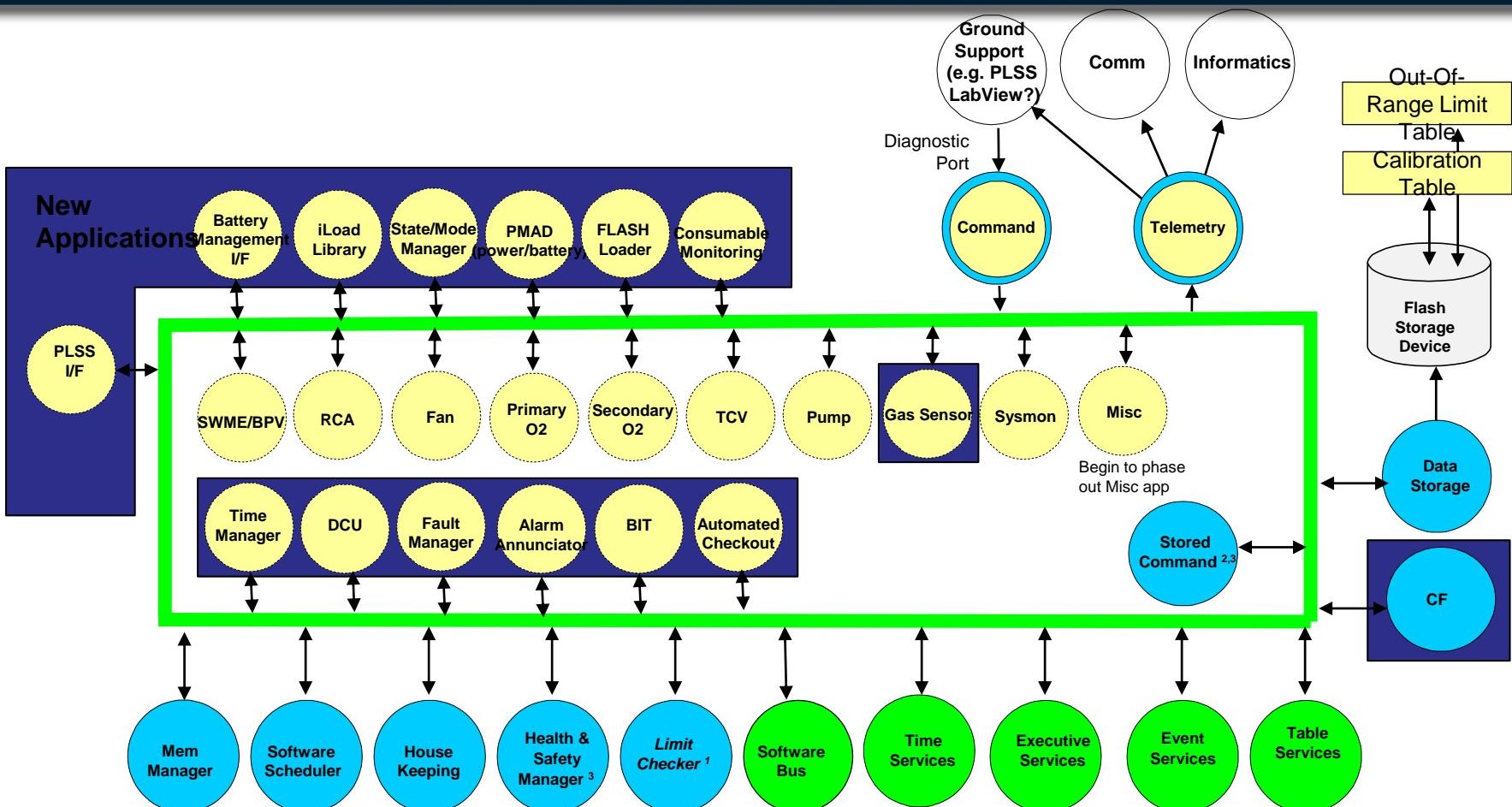


# Downmass Microcapsule Software Flight Software Architecture





# Advanced Space Suite: CWA CFS Software Architecture



<sup>1</sup> Limit Checker provides AEMU C&W

<sup>2</sup> Stored Command provides Checkout & Configuration

<sup>3</sup> Limit Checker, Stored Command, H&S Manager provide Recover & Restore

